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II. BACKGROUND

The emergence of evolving search techniques (e.g., genetic algorithms) has paved the way for innovative character animation solutions. For example, generating human movements without key-frame data. Instead character animations can be created using biologically inspired algorithms in conjunction with physics-based systems. While the development of highly parallel processors, such as the graphical processing unit (GPU), has opened the door to performance accelerated techniques allowing us to solve complex physical simulations in reasonable time frames. The combined acceleration techniques in conjunction with sophisticated planning and control methodologies enable us to synthesize ever more realistic characters that go beyond pre-recorded ragdolls towards more self-driven problem solving avatars. While traditional data-driven applications of physics within interactive environments have largely [1].

This paper presents a survey on video games in learning and education, including patterns and trends in technologies and correlations in popularity with regard to the entertainment industry. The fact that games have the ability to engage and captivate a person's attention for long periods of time, while offering numerous additional benefits, such as, developing high-level thinking skills, is extremely attractive and important. The capacity to unconsciously learn and master complex concepts through video games has enormous benefit in learning [2].

This paper presents a Differential Evolutionary (DE) algorithm for solving multi-objective kinematic problems (eg, end-effector locations, centre-of-mass and comfort factors). Inverse kinematic problems in the context of character animation systems are one of the most challenging and important conundrums. The problems depend upon multiple geometric factors in addition to cosmetic and physical aspects. Further complications stem from the fact that there may be non or an infinite number of solutions to the problem (especially for highly coupled systems) [3].

This article discusses the design and implementation of a holistic game development curriculum. We focus on a technical degree centred around game engineering/technologies with transferable skills, problem solving, mathematics, software engineering, scalability, and industry practices. In view of the fact that there is a growing skills shortage for technically minded game engineers, we must also be aware of the rapidly changing advancements in hardware, technologies, and industry. Firstly, we want a synergistic game orientated curriculum (for a 4-year Bachelor's programme). Secondly, the organisation and teaching needs to adapt to future trends, while avoiding tunnel vision (too game orientated) and support both research and industry needs. Finally, we build upon collaborations with independent experts to support an educational programme with a diverse range of skills. The curriculum discussed in this article, connects with a wide variety of subjects (while strengthening and supporting one another), such as, programming, mathematics, computer graphics, physics-based animation, parallel systems, and artificial intelligence. All things considered, the development and incorporation of procedures into a curriculum framework to keep up with advancements in game technologies is important and valuable. Collaborative learning Computing education programs Contextual software domains Virtual worlds software [4].

A collision detection algorithm that is computationally efficient, numerically stable, and straightforward to implement is a valuable tool in any virtual environment. This includes the ability to determine accurate

proximity information, such as, penetration depth, contact position, and separating normal. We explore the practical and scalable issues of support mapping for use in detecting contact information for convex shapes. While support mapping is a popular technique used in common algorithms, such as, GJK, EPA, and XenonCollide [5].

This paper investigates several methodologies for simulating soft-body objects using a mass-spring approach. The mechanisms are then expanded to include deformation information that can produce results suitable for use in realtime applications where visual impact rather than accuracy is desired, such as video games. Many methods use complex and esoteric methods to achieve physically accurate simulations; we target the mass-spring model because of its simplicity, using creative modifications for diverse visual outcomes [6].

This paper presents a novel method for generating balancing character poses by means of a weighted inverse kinematic constraint algorithm. The weighted constraints enable us to control the order of priority so that more important conditions such as balancing can take priority over less important ones. Maintaining a balancing pose enables us to create a variety of physically accurate motions (e.g., stepping, crouching). Balancing is achieved by controlling the location of the overall centre of mass of an articulated character; while the secondary constraints generate poses from end-effectors and trajectory information to provide continuous character movement. The poses are created by taking into account physical properties of the articulated character, that include joint mass, size, strength and angular limits. We demonstrate the successfulness of our method by generating balancing postures that are used to produce controllable character motions with physically accurate properties; likewise, our method is computationally fast, flexible and straightforward to implement [7].

Deformation mechanics in combination with artistic control allows the creation of remarkably fluid and life-like 3-dimensional models. Slightly deforming and distorting a graphical mesh injects vibrant harmonious characteristics that would otherwise be lacking. Having said that, the deformation of high poly complex shapes is a challenging and important problem (e.g., a solution that is computationally fast, exploits parallel architecture, such as, the graphical processing unit, is controllable, and produces aesthetically pleasing results). We present a solution that addresses these problems by combining a tetrahedron interpolation method with an automated tetrahedronization partitioning algorithm. For this paper, we focus on 3-dimensional tetrahedron meshes, while our technique is applicable to both 3-dimensional (tetrahedron) and 2-dimensional (triangulated planar) meshes. With this in mind, we compare and review free-form deformation techniques over the past few years. We also show experimental results to demonstrate our algorithms advantages and simplicity compared to other more esoteric approaches [8].

In this paper, we examine a ready-to-use, robust, and computationally fast fixed-size memory pool manager with no-loops and no-memory overhead that is highly suited towards time-critical systems such as games. The algorithm achieves this by exploiting the unused memory slots for bookkeeping in combination with a trouble-free indexing scheme. We explain how it works in amalgamation with straightforward step-by-step examples. Furthermore, we compare just how much faster the memory pool manager is when compared with a system allocator (e.g., malloc) over a range of allocations and sizes [9].

Student peer review has long been a method for increasing student engagement and work quality. We present notes on teaching tips and techniques using peer review as a means to engage students interest in the area of computer graphics and interactive animation. We address questions, such as, when feedback fails, why students should be 'trained' on feedback, and what constitutes a 'constructive' review. We present a case

study around the structure and workings of a module-and its success in encouraging collaborative working [10].

The way we engage and communicate with students has rapidly changed over the past decade due to technological advancements. This is most noticeable in web-based subjects with the advent of smart-phones, web-based apps, web-streaming and of course social media. Students who learn and develop for web-based environments must be able to adapt and retrain constantly, not to mention, have both a technical and creative mindsets. This article presents the insights for integrating interactive digital solutions and game-based [11].

Inverse kinematic systems are an important tool in many disciplines (from animated game characters to robotic structures). However, inverse kinematic problems are a challenging topic (due to their computational cost, highly non-linear nature and discontinuous, ambiguous characteristics with multiple or no-solutions). Neural networks offer a flexible computational model that is able to address these difficult inverse kinematic problems where traditional, formal techniques would be difficult or impossible [12].

Unlike traditional animation techniques, which attempt to copy human movement, cognitive' animation solutions mimic the brain's approach to problem solving, ie, a logical (intelligent) thinking structure. This procedural animation solution uses bio-inspired insights (modelling nature and the workings of the brain) to unveil a new generation of intelligent agents. As with any promising new approach, it raises hopes and questions; an extremely challenging task that offers a revolutionary solution, not just in animation but to a variety of fields [13].

The Fourier transform plays a crucial role in a broad range of signal processing applications, including enhancement, restoration, analysis, and compression. Since animated motions comprise of signals, it is no surprise that the Fourier transform has been used to filter animations by transforming joint signals from the spatial domain to the frequency domain and then applying filtering masks. However, in this paper, we filter motion signals by means of a new approach implemented using hyper-complex numbers [14].

The proliferation of digital technologies in education is leading to a new academic era that is both chaotic and opportunistic. The educational landscape is evolving-and so are staff and students-to meet tomorrow's challenges and needs, including curricula, mindsets, environments, and tools [15].

The inherent limitations in conventional animation techniques and possible solutions through optimisation and machine learning paradigms. For example, going beyond prerecorded animation libraries towards more intelligent self-learning models. These models present a range of difficulties in real-world solutions, such as, computational cost, flexibility, and most importantly, artistic control. However, as we discuss in this chapter, advancements in massively parallel processing power and hybrid models provides a transitional medium for these solutions (best of both worlds). We review trends and state of the art techniques and their viability in industry. A particular area of active animation is selfdriven characters (i.e., agents mimic the real-world through physics-based models). We discuss and debate each techniques practicality in solving and overcoming current and future limitations [16].

A controllable stepping method for procedurally generating upright biped animations in real-time for three dimensional changing environments without key-frame data. In complex virtual worlds, a character's stepping location can be limited or constrained (eg, on stepping stones). While it is common in pendulum-based stepping techniques to calculate the foot-placement location to counteract disturbances and maintain a controlled speed while walking (eg, the capture-point), we specify a foot location

based on the terrain [17].

Developing online multiplayer games is an exciting and important topic to learn, not just because of entertainment value, but also the ability to manage multi-user interactions online. This course uses step-by-step game-based examples to teach multiplayer web-based gaming concepts combined with tutorials, explanations and projects. Ultimately the goal of this course is to help you create dynamic online web-based solutions that users can interact with in an engaging, fun and playful way (not just the software but also other users [18].

WebGPU API came a new shader language known as 'WGSL' which is short for 'WebGPU'. Introduce you to the basics of the WebGPU API [19].

We present a real-time technique of generating reactive balancing biped character motions for used in time critical systems, such as games. Our method uses a low- dimensional physics-based model to provide key information, such as foot placement and postural location, to control the movement of a fully articulated virtual skeleton. Furthermore, our technique uses numerous approximation techniques, such as comfort reasoning and foot support area, to mimic real-world humans in real-time that can respond to disturbance [20].

Linear Complementary Problem (LCP) Solvers as a method for implementing real-time physics for games. This chapter explains principles and algorithms with practical examples and reasoning. When first investigating and writing a solver, one can easily become overwhelmed by the number of different methods and lack of implementation details, so this chapter will demonstrate the various methods from a practical point of view rather than a theoretical one; using code samples and real test cases [21].

III. CONCLUSION

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